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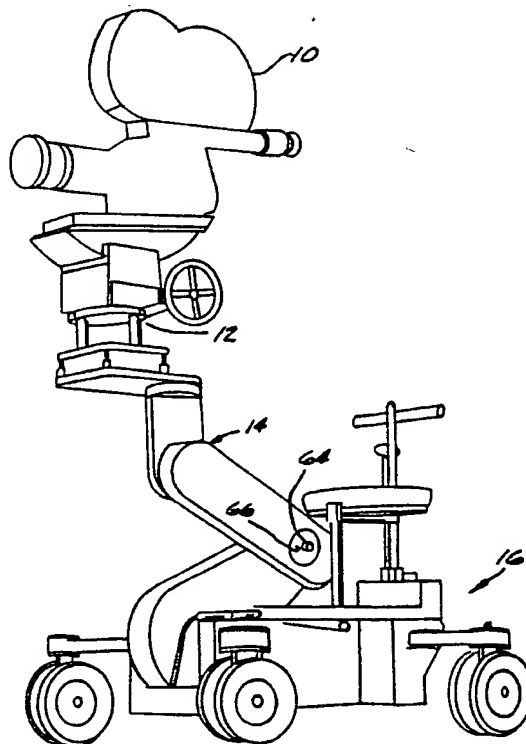
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(54) Motorized tang drive system.

(57) The present invention provides an apparatus for controlling operation of a fluid control valve. In the preferred embodiment, the present invention operates a hydraulic control valve to operate a hydraulic apparatus. The control system of the present invention permits the pre-selected adjustable control of the acceleration and speed of movement of the apparatus to be controlled. Additionally, the control system permits the selection of pre-determined movement limits within which the operation of the hydraulic apparatus may be contained. The control apparatus also senses the amount of actuation of the control valve.



*FIG. 1.*

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## MOTORIZED TANG DRIVE SYSTEM

### Background

The present invention relates to devices for remote actuation of control valves, and in particular, rotary control valves.

Numerous applications which utilize valves to control fluid flow are well known in the art. The actuation of such valves may also often times control more than merely the flow of fluid. For example, the use of hydraulic components relies heavily on valves to control the flow of hydraulic fluid, thereby controlling a related hydraulic component. Valves for controlling the flow of incompressible fluids such as hydraulic fluid are numerous. Such valves may be rotary actuated such as those described in Chapman, 4,109,678; 1978 and Chapman, U.S. Patent Application Serial No. , filed on October 1, 1986, the disclosures of which are hereby referred to and incorporated herein in full by reference. In many situations, it is desirable to provide a means by which the operation of a such a control valve may be operated under adjustable preselected limits and conditions.

In the utilization of motion picture cameras, video cameras or other photographic equipment, it is often desirable to provide a means by which the camera or equipment may be moved during equipment operation. For example, it is often desirable to change the vertical position of a motion picture or video camera while the camera is operating. In order to obtain a high quality motion picture or video, it is necessary to provide a means which will permit such movement of the camera in a smooth and shock free manner. Typically, movement of the camera in the vertical direction during filming with a camera or the like will be from one known level to a second known level. Therefore, it is desirable to provide a means by which a camera or other photographic equipment may be vertically moved in a smooth and shock free manner from a first elevation to a second preselected elevation.

### Summary of the Present Invention

The present invention provides an apparatus for controlling the actuation of a fluid control valve. The preferred embodiment of the present invention acts to control a rotary fluid control valve. The present invention permits the speed at which the components operate and the movement of the various components within preselected motion limits and the acceleration of the components to be controlled. In addition, means to remotely actuate the

present invention are provided. As such, it is an object of the present invention to provide an apparatus which permits the control of a fluid control valve within such adjustable pre-selected constraints. Other and more detailed objects of the present invention will become apparent to those skilled in the art after reviewing the present disclosure.

### Description of the Drawings

Figure 1 is a perspective view of a mobile dolly having a motion picture of video camera mounted thereon, on which the preferred embodiment of the present invention may be used;

Figure 2 is a top view of the preferred embodiment of the present invention;

Figure 3 is a cross-sectional view of the preferred embodiment of the present invention;

Figure 4 is a top view of the printed circuit board to which the preferred electrical control circuitry is connected;

Figure 5 is a schematic illustration of the preferred electronic control circuitry of the preferred embodiment of the present invention;

Figure 6 is a schematic illustration of the preferred electronic circuitry of the component positioning sensor in the preferred embodiment of the present invention;

Figure 7 is a schematic illustration of the preferred electronic circuitry of the motion limiting means of the preferred embodiment of the present invention;

Figure 8 is a schematic illustration of the preferred electronic circuitry of the component speed control means of the preferred embodiment of the present invention; and

Figure 9 is a schematic illustration of the power supply means.

### DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT

For purposes of example, the preferred embodiment of the present invention is described herein in conjunction with a mobile dolly having a hydraulic extendable arm which is operated through a rotary control valve 12. As this description is merely for purposes of example, no limitations of the appended claims should be implied or construed as a result of this description.

As illustrated in Figure 1, photographic equipment such as a video camera or a movie camera 10 is often mounted on a mobile dolly 16 having an extendable arm 14. An example of such a mobile dolly may be found in Chapman, U.S. Patent No. 4,360,187; 1982, the disclosure of which is hereby referred to and incorporated herein in full by reference. The rotary actuated control valve 12 includes a rotatable actuation member 18 which is supported by bearings 20. The rotatable valve actuation member 18 has engagement notches 33 formed in the end of the member 18 which extends from the dolly 16.

Referring to Figures 2 and 3, the present invention includes a housing 22. A rotatable actuator 24 and a rotatable support collar 27 are mounted in the housing 22 through bearings 26. As illustrated in Figure 3, engagement pawls 34 extend from the ends of the actuator 24 and support collar 27 and engage which engagement notches 33 when the present invention is connected to the mobile dolly 16. Similarly, engagement notches 36 are provided in the opposite ends of the actuator 24 and the rotating support collar 27 so as to permit manual actuation of the control valve 12 through not shown manual actuator means.

The present invention is preferably mounted to a dolly 16 by engaging the housing 22 with the shoulder flange 38 extending from the dolly 16 about the valve actuation member 18. Upon aligning the engagement pawls 34 with the valve actuation member engagement notches 33, the present invention may be securely maintained in the proper position by means of a thumb screw 40 or the like. So configured, movement of the dolly extendable arm 14 is controlled by rotation of the rotatable actuation member 24 and support collar 27.

In order to accomplish rotation of the actuator 24 and support collar 27 of the present invention, a motor means such as an electric motor 28 is provided. Power from the electric motor 28 is transmitted to the actuator 24 and support collar 27 through a worm 30 and worm gear 32.

As will be understood by those skilled in the art, the speed at which the extendable arm moves depends upon the amount which the rotary control valve 12 is opened. The more the valve is opened, the faster the arm will move. Similarly, the acceleration of the arm may also be controlled by controlling the speed with which the rotary hydraulic control valve 12 is opened or closed. In the present invention, the rotary hydraulic valve 12 is controlled through electronic means which operate to control the motor means linked to the rotary control valve

12. As described hereinafter, the present invention includes speed control means 42, operation limiting means 44, acceleration selection means 46 and valve actuator sensor means 48.

Referring to Figures 4-9, the preferred electronic circuitry of the present invention and its operation will hereinafter be described. As is illustrated in the figures, the preferred electronic circuitry of the present invention includes a differential amplifier 58 and a driver 60. The differential amplifier 58 receives signals from the motion limiting means 44 and the position sensor means 62. The driver receives inputs from the valve centring center 48 and the speed control means 32 which electrically links the differential amplifier 58 with the driver 60.

In the preferred embodiment, the arm position sensor means 62 includes, as is illustrated in Figure 6, a variable resistor means such as a potentiometer connected to a ground at one end and a known voltage VCC at the other. As shown in Figure 1, the potentiometer 64 of the position sensor means 62 is preferably connected to the pivoting means 66 connecting the first and second components of the extendable arm 14.

Figure 7 illustrates the preferred electronic circuitry which provides for movement control means. As illustrated in that figure, alternative variable resistance means such as two potentiometers 66 are provided. The two potentiometers 66 are controlled and may be varied through knobs 67 which are situated on the face of the present invention as illustrated in Figures 2 and 3.

A switch 68 to selectively connect the voltage VCC to the alternative potentiometers 66 is provided. The switch 68 enables one of the two alternative potentiometers to be linked with the circuit depending upon whether the arm is being extended or retracted. Both the position sensor means 62 and the movement control means 44 are electrically connected to the differential amplifier 58 at point C. As it will be understood by those skilled in the art, the transistor 70 of the differential amplifier 58 provides an inverted voltage to point B of the circuit depending upon the comparison of the signals received from the positive and negative transistor terminals. This voltage is then attenuated through the speed control means 42, illustrated in Figure 8, and subsequently fed to the driver 60.

The speed control means 42 includes alternative variable resistor means such as two potentiometers 72 which may be alternatively engaged through the switch 68 depending upon whether the arm is being extended or retracted. The switch 68 may be remotely placed so as to enable the remote actuation of the valve 12. Similar to the movement control means 44, the two speed control

potentiometers 72 are controlled and may be varied by knobs 74 which are positioned on the face of the present invention as illustrated in Figures 2 and 3.

In addition to the above signals, the driver additionally monitors the position of the rotary control valve 12 through a valve centering sensor 48. As illustrated in Figure 5, the valve centering sensor 48 is preferably a variable resistance means such as a potentiometer 50 connected to a ground at one end and a known voltage VCC at the other. In the preferred embodiment, the potentiometer 50 is mounted to the housing 22 through bearings 56 or the like. The variable resistance of the potentiometer 50 is controlled by rotation of the valve actuator 24 through spur gears 52 and 54, as is best illustrated in Figure 3.

In the driver position 60 of the preferred electronic circuitry, an integrated circuit such as a UIMC1458 is used as a window comparator. As is understood by those skilled in the art, although a certain voltage is always present at point A of the circuit, unless this voltage exceeds the detent zone of the window comparator, the electronic motor 28 will see no differential voltage and therefore will not operate to drive the valve in either direction. Alternatively, where the voltage at point A is outside the detent zone of the window comparator. The motor 28 will be driven by a voltage differential in one direction or the other, thereby rotating the rotary control valve in either the clockwise or counter clockwise direction. This rotation of the rotary control valve 12 acts to extend or retract the extendable arm through the flow of hydraulic fluid.

As is illustrated in Figure 2, an acceleration switch 46 is also provided. Referring to Figure 4, the acceleration of the arm is controlled by varying the voltage of VCC applied to the circuit. In the preferred embodiment, a switch 73 acts to selectively provide 18 or 27 volts as illustrated in Figure 9. As it will be understood to those skilled in the art, the higher the voltage, the faster the electric motor will turn a proscribed amount. Alternatively, as will be understood to those skilled in the art, the voltage supply could be varied through alternative circuitry such as an additional potentiometer, which potentiometer would permit the variation of the voltage reaching the motor. The speed at which the motor operates will directly control the speed at which the rotary control valve will open and close, thereby directly controlling the acceleration of the arm to the preselect speed. Similarly, variation of the variable resistor means in the speed control means 42 will alter the voltage differential presented to the motor, thereby altering the amount of rotation of the motor. Again, the more the motor and hydraulic control valve 12 rotates, the faster the arm will extend or retract.

As the above description is for purposes of example, persons skilled in the art will understand that alternative embodiments of the present invention, including alternative electronic control circuitry is possible without departing from the spirit of the present invention as embodied in the appended claims.

## Claims

1. A motorized tang drive system for controlling movement of an extendable boom arm, said boom arm being actuated by a rotary hydraulic control valve, comprising, an actuator, said actuator being arranged to selectively operate the control valve means to actuate said actuator, and control means, said control means including means to control the speed at which said actuator actuates the control valve, means to control the amount of actuation of said actuator, means to determine the amount of actuation of said actuator, and means to determine the position of the extendable boom arm.

2. A motorized tang drive system as set forth in Claim 1 wherein said means to actuate said actuator includes a worm and worm gear, said worm and worm gear being driven by a motor means.

3. A motorized tang drive system as set forth in Claim 2 wherein said means to control the speed at which said actuator actuates includes a switch means, said switch means being arranged to selectively provide additional power to said motor means.

4. A motorized tang drive system as set forth in Claim 1 wherein said means to control the amount of actuation of said actuator include adjustable resistance means and electronic circuitry connecting said adjustable resistance means to said control means.

5. A motorized tang drive system as set forth in Claim 1 wherein said means to sense the amount of actuation of said actuator include adjustable resistance means, said adjustable resistance means being adjustable in response to actuation of said actuator, and electronic circuit means connecting said adjustable resistance means to said control system.

6. A motorized tang drive system for controlling operation of a hydraulic component, comprising, a rotary control valve, an actuator, said actuator being arranged to selectively operate the rotary control valve, means to actuate said actuator, and means to control said actuator including means to control the acceleration of the apparatus movement, means to control the speed at which the

apparatus operates, means to limit the movement of the apparatus within pre-selected constraints and means to remotely operate said actuator.

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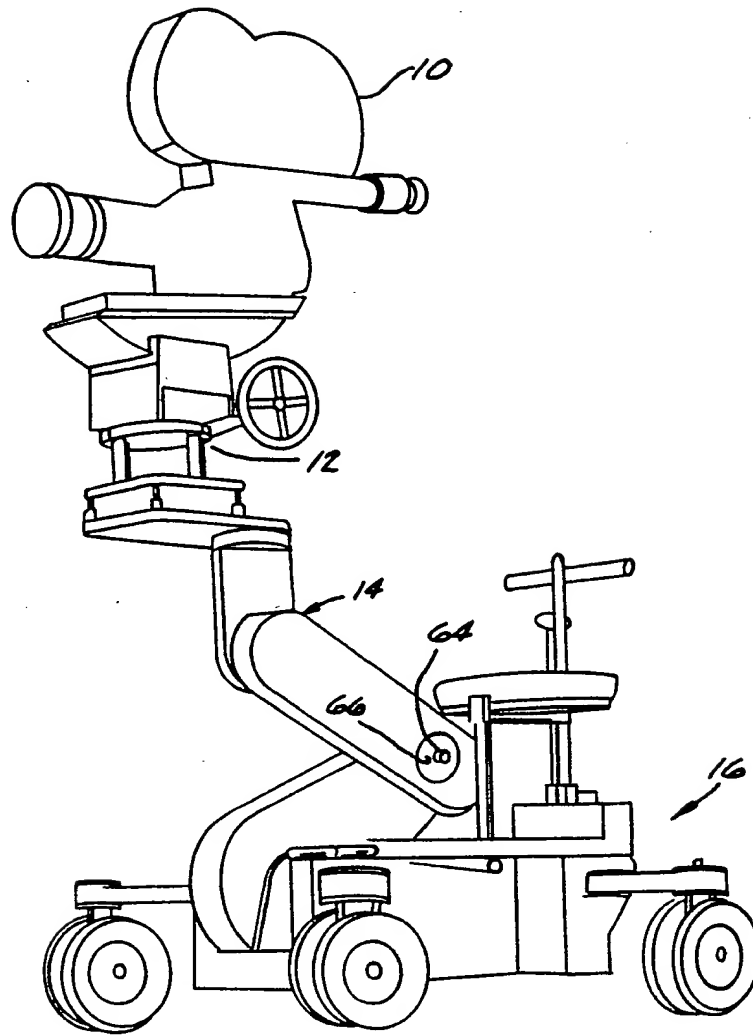


FIG. 1.

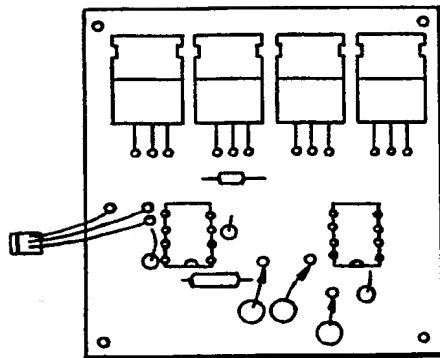


FIG. 4.

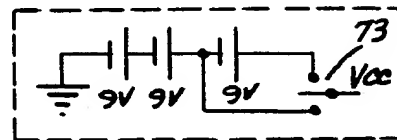


FIG. 9.

FIG. 2.

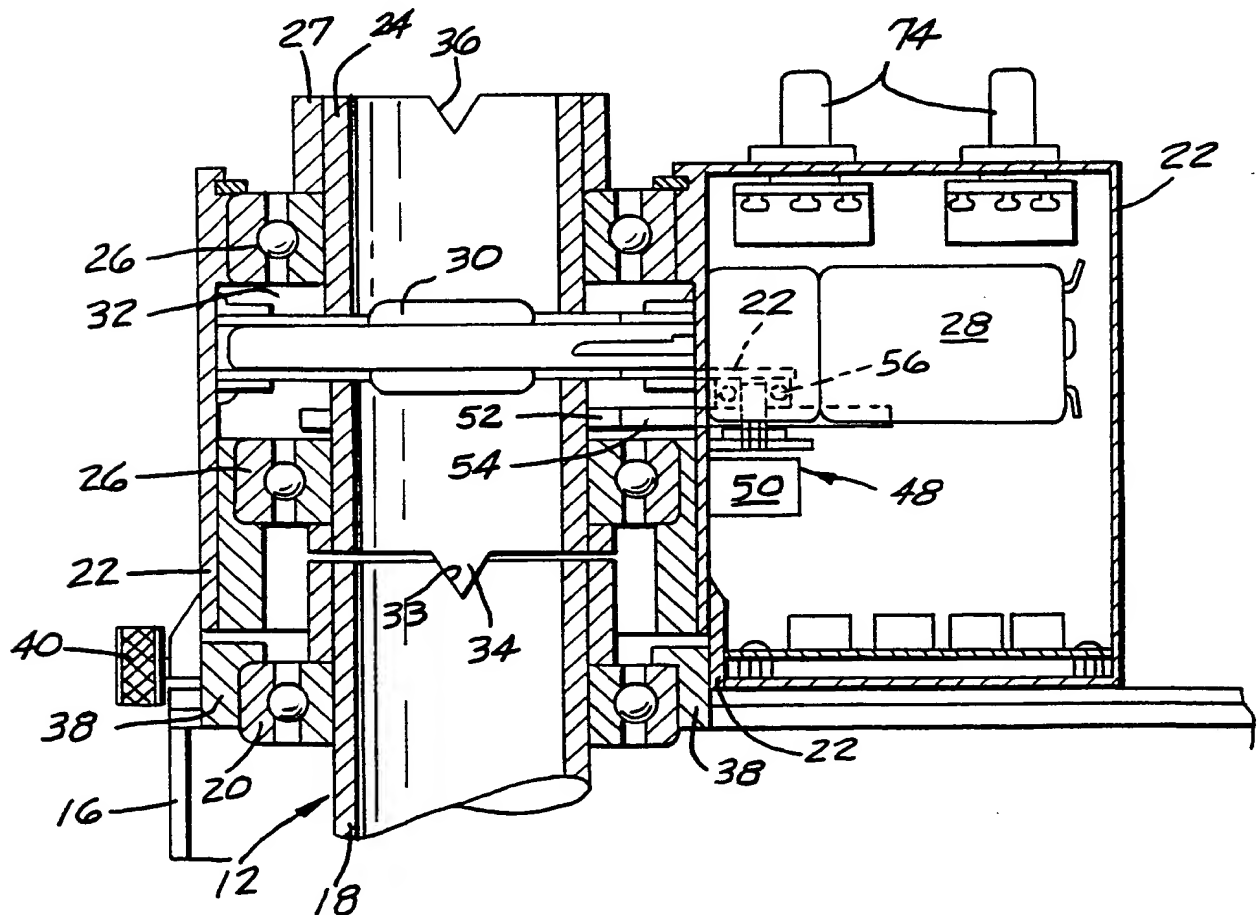
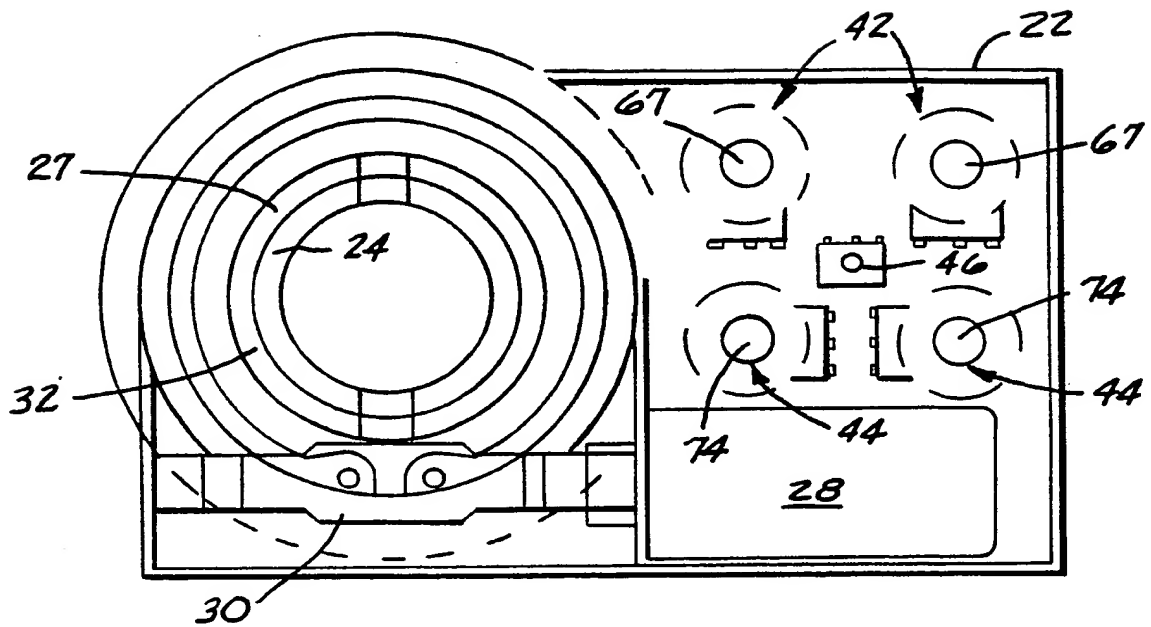


FIG. 3.

FIG. 5.

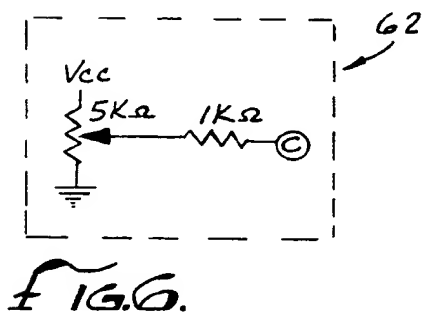
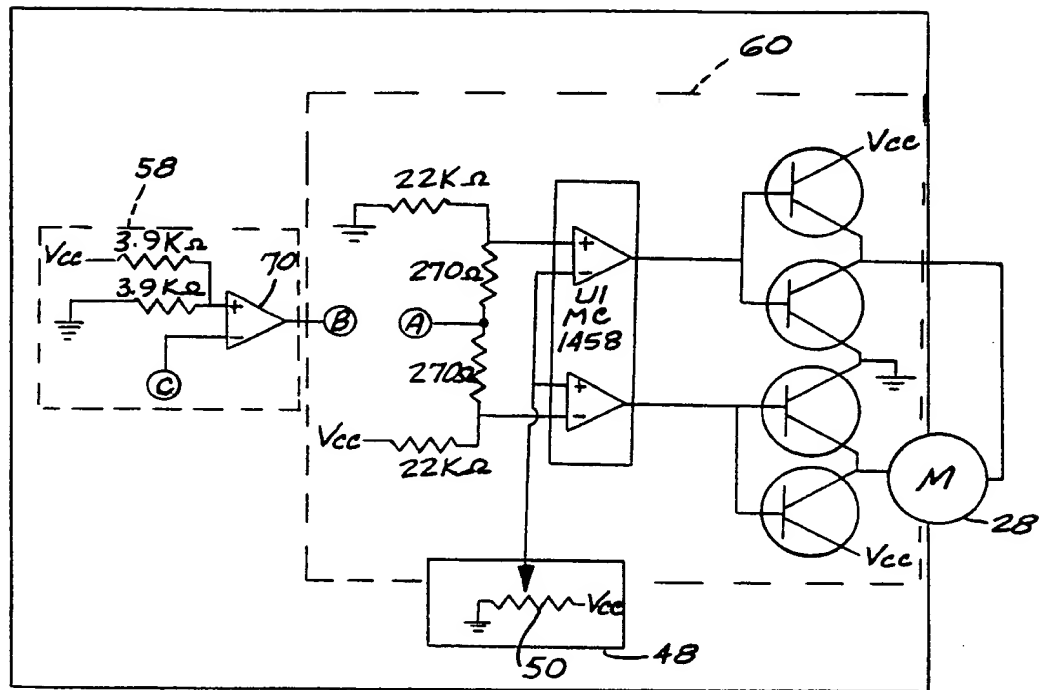


FIG. 6.

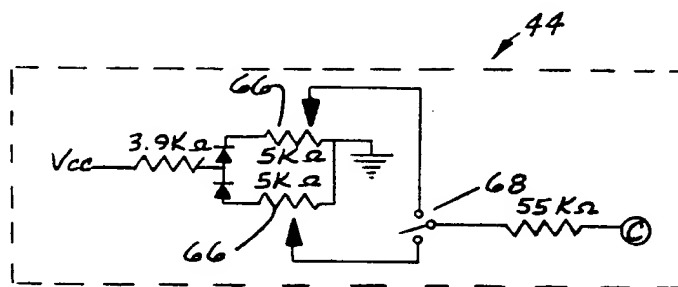


FIG. 7.

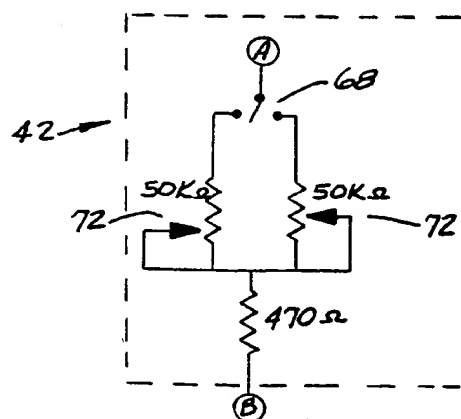


FIG. 8.



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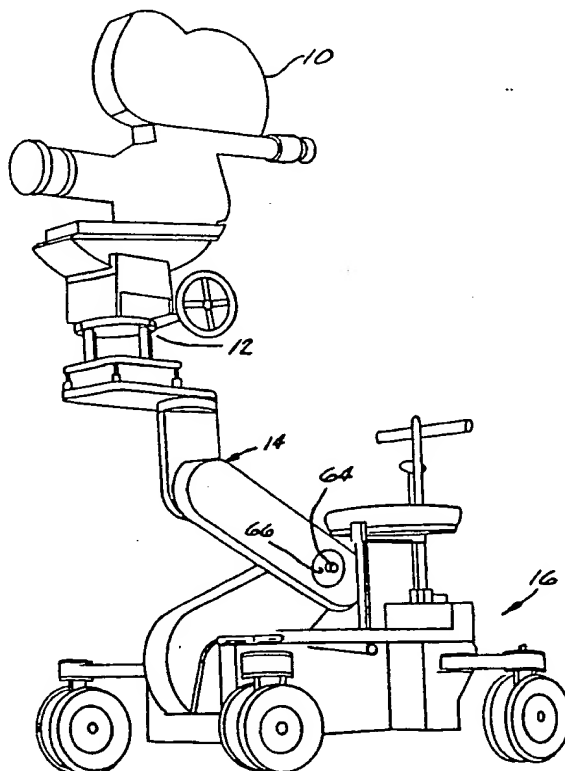
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*Fig. 1.*

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DOCUMENTS CONSIDERED TO BE RELEVANT			
Category	Citation of document with indication, where appropriate, of relevant passages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (Int. Cl. 4)
A	GB-A-1 040 906 (J.L. FISHER) * Page 4, lines 76-125; page 5, lines 28-32 *	1	F 16 K 11/14 B 66 F 11/04 F 16 K 31/04
A	US-A-3 994 179 (J.N. MORRELL) * Claim 3 *	2	
A	US-A-3 103 257 (P. RICHARDS)		
A	FR-A-1 402 363 (ROTORK ENGINEERING CO. LTD)		
A	EP-A-0 249 559 (BERTIN & CIE)		
A	DE-B-1 179 455 (OPTISCHE WERKE G. RODENSTOCK)		
			TECHNICAL FIELDS SEARCHED (Int. Cl. 4)
			F 16 K 11/00 F 16 K 31/00 B 66 F 11/00 F 16 M 11/00 F 15 B 13/00 F 15 B 9/00 H 02 P 7/00
The present search report has been drawn up for all claims			
Place of search THE HAGUE		Date of completion of the search 17-07-1989	Examiner DE SMET F.P.
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